

# Online Course Development for eVehicle Motor Control.

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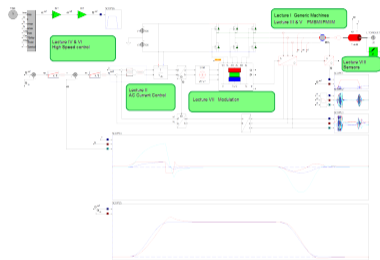
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Mai 24 , 2024

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- 2 Electric Driveline Design
- 3 Field Oriented Control
- 4 Modulation
- 5 Cascaded Speed-Current control
- 6 Field Weakening
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- 8 Conclusions

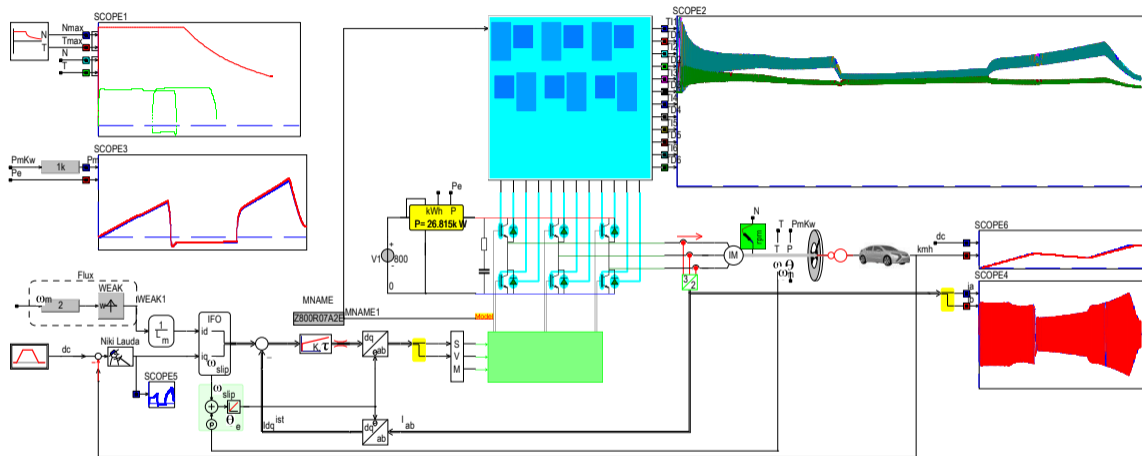
Task:  
eMobility & Electric Driveline and Control

- Driveline design
- Field Oriented Control
- IPM control
- Experimental assignment

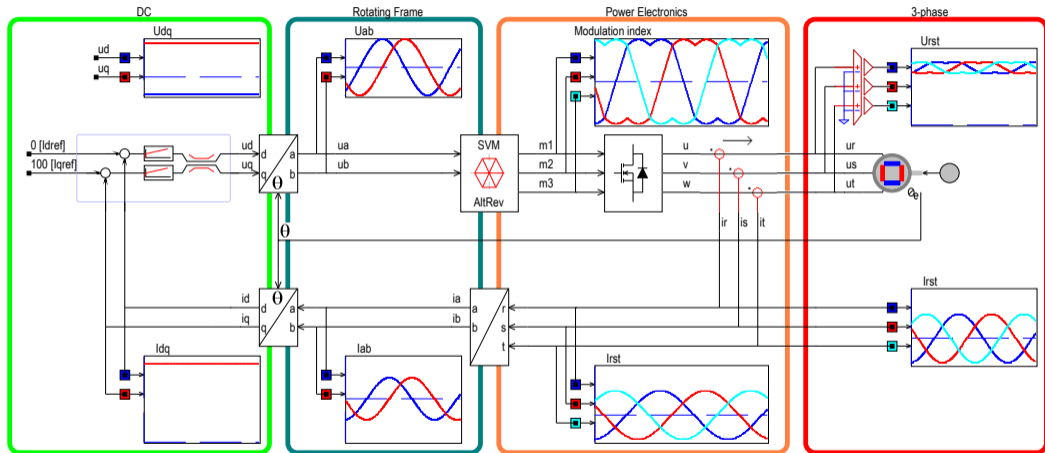


Control Design

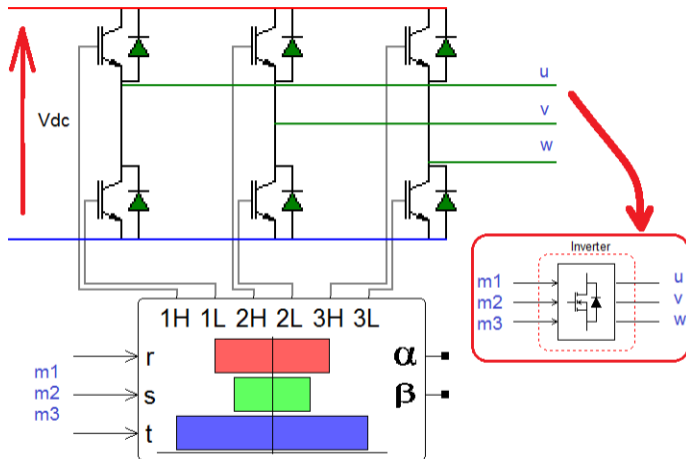
Design Tools & Simulation & Hardware Trainer



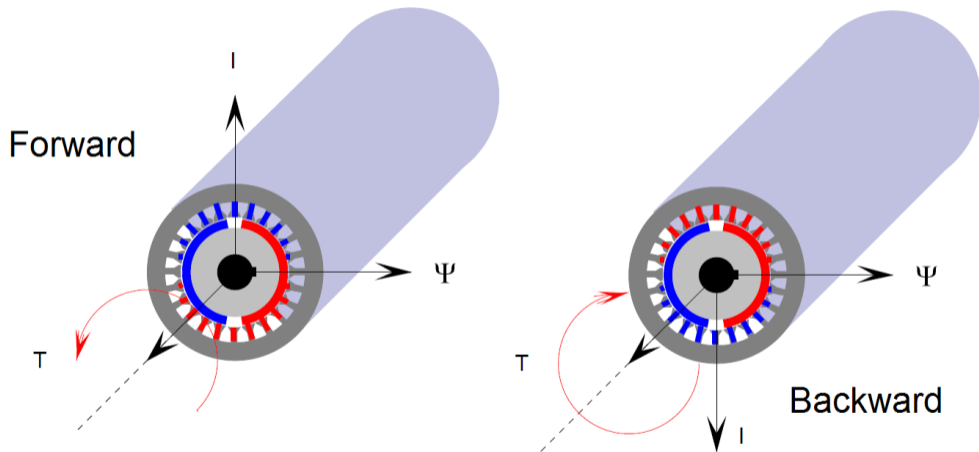
Simulation of the control and losses in an electric vehicle with interior permanent magnet synchronous machine and Field-Oriented Control in Caspoc



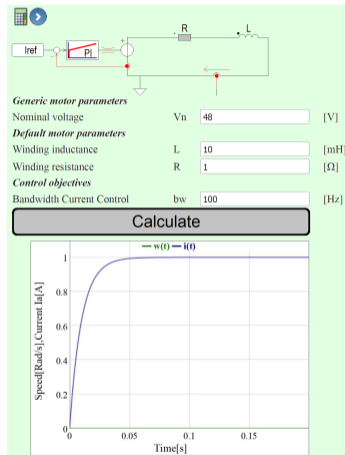
Field Oriented Control of a PMSM machine explained using a simulation in Caspoc



Inverter represented by a single functional block and by a detailed animated block, that can be both used in the simulation in Caspoc, depending on the level of detail required.

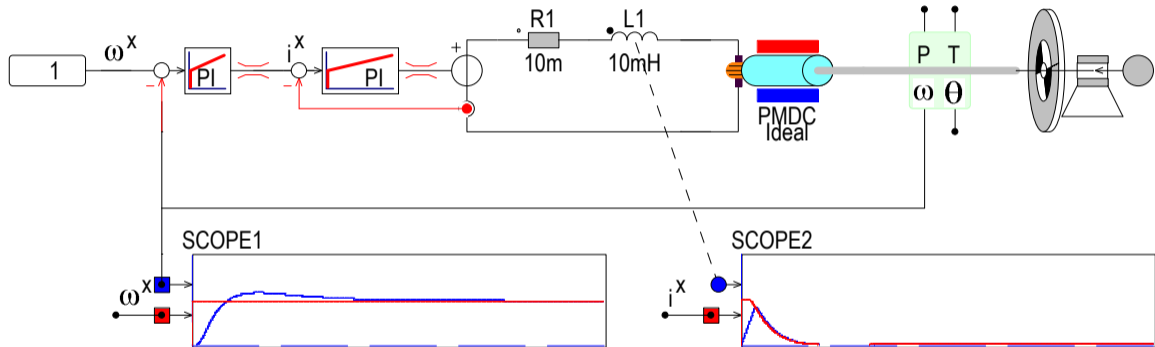


Forward or backwards rotation controlled by  $I_{dq}$

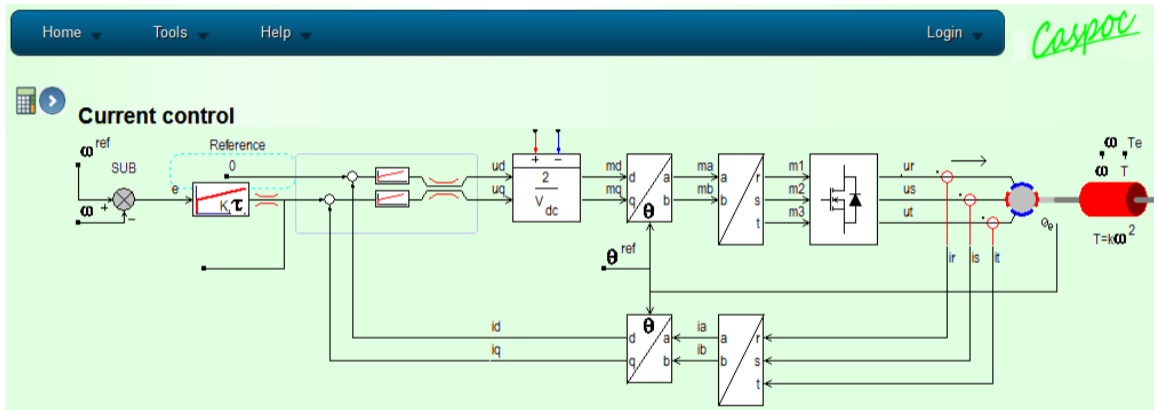


Current control of an RL load using a PI controller.

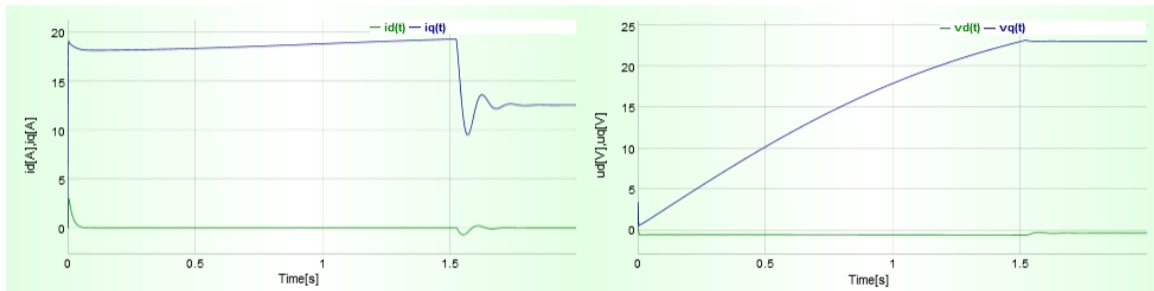




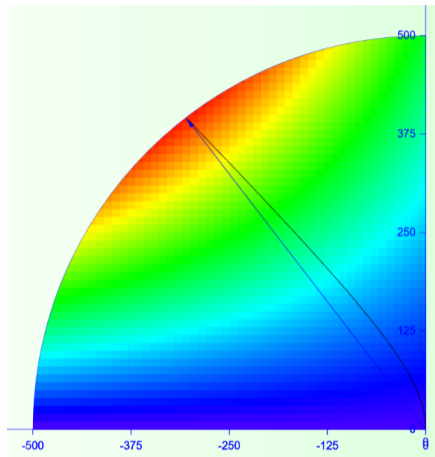
Cascaded speed-current control of a generic machine.



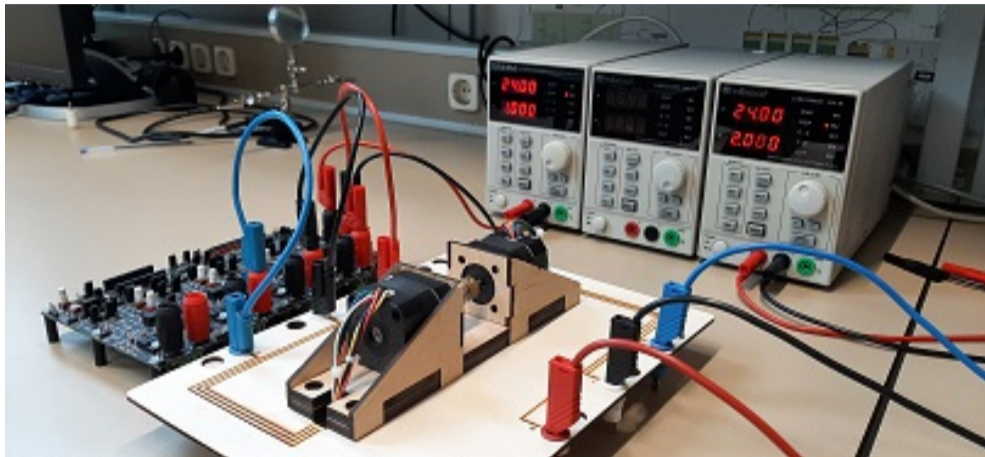
Current control of an Interior Permanent Magnet Synchronous Machine using two cascaded PI controllers.



Voltage and current of the field oriented control, for the Interior Permanent Magnet Synchronous Machine using two cascaded PI controllers.



Normalized Torque as function of  $i_{dq}$  in an IPM.



Laboratory setup for measuring voltage, current, torque and speed of two coupled AC motors powered by a Universal Four Leg

- Drive Line design and Cascaded Speed-Current control
- Field Oriented Control & Field Weakening
- Design tools and Simulation
- Hardware Trainer

Thank you!

<https://www.dc-lab.org>

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